## **MECA0025** - Sattelite Engineering

### Space propulsion

December 4, 2024





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Introduction Classification Thrust, acceleration and specific impulse

Gas expansion Principles Thermal rockets Solid propellant Monopropellant liquid rocket Bipropellant liquid rocket

Electric propulsion Principles Gridded ion thrusters Hall effect thrusters

Air Breathing Electric Propulsion





Introduction Classification Thrust, acceleration and specific impulse

Gas expansion

Electric propulsion

Air Breathing Electric Propulsion

#### Introduction Classification - aeronautic vs space propulsion

Thrust = reaction to *acceleration* of propellant mass

 $\mathcal{T}=\dot{m}_p(v_e-v_0)$ 

#### Aeronautics vs space propulsion

	Aeronautics	<b>Space</b> Sattelite and spacecraft	Launcher	VLEO <sup>1</sup> / ABEP <sup>2</sup>
Atmosphere	air	none	atmosphere	outer atmosphere
Propellant	air ingestion	on board	on-board	air collection
Aim	compensate drag	accumulate speed change position	defy gravity	compensate drag
Dependence	$p_{amb}, T_{amb}$ flight velocity	none	P <sub>amb</sub>	$p_{amb}, T_{amb}$ flight velocity
Performance Thrust delivery	fuel/energy continuous	propellant mass accumulated	propellant mass continuous	energy continuous

<sup>1</sup>Very Low Earth Orbit

<sup>2</sup>Air Breathing Electric Propulsion



#### Introduction Thrust, acceleration and specific impulse

 $\bullet \ \ thrust = reaction \ to \ acceleration \ of \ the \ propellant$ 

 $\mathcal{T} = \dot{m}_e c_e \, \left[ N 
ight]$ 

• effective exhaust velocity

 $c_e = rac{\mathcal{T}}{\dot{m}} \; [m/s]$ 

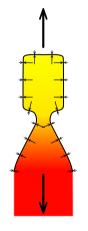
• specific impulse: propellant mass efficiency

$$\mathcal{I}_{sp} = rac{\mathcal{T}}{\dot{m}g} = rac{c_e}{g} \ [s]$$

• cumulative acceleration " $\Delta v$ "

$$\Delta v(t) = \int_0^t \frac{\mathcal{T}(t)}{m} dt$$

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# Introduction Thrust, acceleration and specific impulse - $\Delta v$



$$\Delta v_1 = \sqrt{\frac{GM}{r_1}} \sqrt{\frac{2r_2}{r_1 + r_2} - 1}$$
  
 $\Delta v_2 = \sqrt{\frac{GM}{r_2}} \sqrt{1 - \frac{2r_1}{r_1 + r_2}}$ 

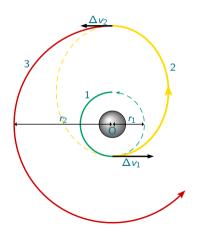
extremely short (instantaneous) "kick"  $\rightarrow$  very high thrust • Launch: overcome gravity

$$\Delta v = \int \frac{g(y) \, dy}{v}$$

short duration  $\rightarrow$  high thrust

- ${lackbdyle}$  deep space: long duration  $\rightarrow$  low thrust, high specific impulse
- positioning and deorbiting (design for demise)





# Introduction Thrust, acceleration and specific impulse - $\Delta v$

	Mission	$\Delta v$	$\mathcal{T}$	duration	
- Typical values	Launch to low orbit Low to high orbit (kick motors)	$\geq$ 9500 $m/s$ pprox 4200 $m/s$	200 tons few tons	8 min seconds	continuous continuous
	High orbit to Mars Escaping solar system Control and positioning	$\approx 3400 m/s \\ + = 8500 m/s$	- - mN to 10 N	-	continuous continuous pulsed



#### Introduction Thrust, acceleration and specific impulse - importance of specific impulse

Payload  $m_l$ , engine  $m_m$  and propellant mass  $m_p$ 

$$m(t) = m_l + m_m + m_p(t) \qquad \Rightarrow \qquad rac{dm}{dt} = rac{dm_p}{dt} = -\dot{m}_e$$

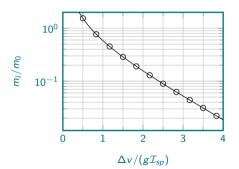
Tsiolkowski equation

$$m\frac{dv}{dt} = g\mathcal{I}_{sp}\dot{m}_e = -g\mathcal{I}_{sp}\frac{dm_p}{dt} = -g\mathcal{I}_{sp}\frac{dm}{dt}$$
$$\Rightarrow m(t) = m(0) \ e^{-\frac{\Delta v}{\mathcal{I}_{spg}}}$$

Propellant mass for given  $\Delta v$ 

$$m_{p,\Delta v} = m(0) - m(t) = m(0) \left(1 - e^{-\frac{\Delta v}{g\mathcal{I}_{sp}}}\right)$$

high  $\mathcal{I}_{sp} 
ightarrow$  higher payload





#### Introduction Thrust, acceleration and specific impulse

#### Considerations for thruster choice

- which  $\Delta v$  ?
- ${\ensuremath{\, \bullet \,}}$  over short or long time span  $\rightarrow$  low or high  ${\ensuremath{\mathcal T}}$
- how much propellant weight can we afford  $\rightarrow$  specific impulse  $\mathcal{I}_{sp}$
- single burn *or* multiple burns
- ${\ensuremath{\bullet}}$  variation of thrust required  $\rightarrow$  can we pulse the thruster
- dry weight of the motor and its auxiliaries (e.g. reservoir, power generator)
- power consumption, generation and storage





#### Introduction

Gas expansion Principles Thermal rockets Solid propellant Monopropellant liquid rocket Bipropellant liquid rocket

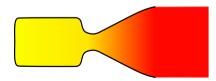
Electric propulsion

Air Breathing Electric Propulsion

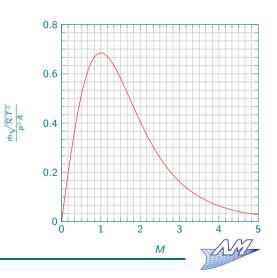
### Gas expansion Principles - convergent-divergent nozzle

- Reservoir conditions  $p^{\circ}$ ,  $T^{\circ}$
- Mach number M = v/a
- Isentropic acceleration / deceleration
  - $T = T^{\circ}/f(M)$   $p = p^{\circ}/(f(M))^{\frac{\gamma}{\gamma-1}}$
- Mass flow ifo total conditions

$$\dot{m} = \rho v A = \frac{p^{\circ} A}{\sqrt{\mathcal{R} T^{\circ}}} F(M)$$



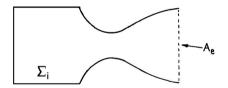
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#### Gas expansion Principles - thrust generation

#### Thrust

$$\mathcal{T}=\dot{m}_e v_e + \left(p_e - p_a
ight)A_e$$





$$c_e = \frac{\mathcal{T}}{\dot{m}_e} = \frac{\mathcal{T}}{\underbrace{\overset{} p^{\circ} A_t}_{\mathcal{C}_{\mathcal{T}}}} \underbrace{\overset{} p^{\circ} A_t}_{\mathcal{C}^*}$$

- thrust coefficient  $C_T$ : performance of nozzle;
- $\bullet\,$  characteristic velocity  $\mathcal{C}\colon$  propellant properties and feed conditions.



### Gas expansion Principles - Operation ifo altitude

#### In attached regime of the de Laval nozzle, *i.e.*

- underexpanded
- overexpanded with oblique shocks outside nozzle

we find

$$\mathcal{T} = \dot{m}_e v_e + (p_e - p_a) A_e \qquad \Rightarrow \qquad \mathcal{C}_{\mathcal{T}} = \frac{I}{p_e^{\circ} A_e}$$

$$_{\mathcal{T}} = \frac{\mathcal{T}}{p^{\circ}A_t} = \left( \left( 1 + \gamma M_e^2 \right) \frac{p_e}{p^{\circ}} - \frac{p_a}{p^{\circ}} \right) \frac{A_e}{A_t}$$

 $\mathcal{C}_\mathcal{T}$  depends on

- area ratio  $A_e/A_t$
- pressure ratio  $NPR = p^{\circ}/p_a$
- $\bullet$  heat capacity ratio  $\gamma$

In separated regime (= heavily overexpanded), the nozzle is "shortened" to the location of separation/shock



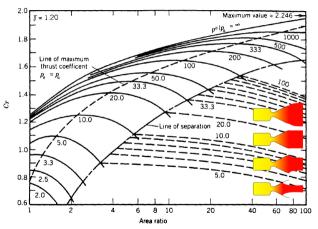
### Gas expansion Principles - thrust coefficient

#### $\mathcal{C}_\mathcal{T}$ depends on

- altitude, in particular nozzle pressure ratio p°/pa
- nozzle geometry, in particular exit to throat area ratio  $A_e/A_t$

Observations and consequences for launchers/space thrusters

- for each altitude/pressure ratio optimal area ratio → area ratio is compromise for launchers
- $\bullet\,$  maximum thrust in vacuum, increases with area ratio  $\rightarrow\,$  maximal area ratio for space thrusters
- separation is observed up to a certain altitude/pressure ratio  $\rightarrow$  launchers: high feed pressure  $p^{\circ}$  to reduce separation





### Gas expansion Principles - characteristic velocity

$$\mathcal{C}^* = \frac{p^{\circ}A_t}{\dot{m}_e} = \frac{p^{\circ}A_t}{\rho^*a^*A_t} = \frac{1}{\gamma} \frac{p^{\circ}}{p^*} \sqrt{\frac{T^*}{T^{\circ}}} \sqrt{\gamma \mathcal{R} T^{\circ}} = f(\gamma) \sqrt{\frac{\gamma \mathcal{R}^* T^{\circ}}{\mathcal{M}}}$$

#### Characteristic velocity depends on

- chamber/combustion temperature  $\mathcal{T}^{\circ}$
- $\bullet \ \ \text{molar mass} \ \mathcal{M}$

#### Hence

- lighter molecules have higher  $c_e \ / \ \mathcal{I}_{sp}$  for same  $T^{\circ}$
- $\bullet\,$  combustion rockets:  ${\mathcal T}^\circ$  determined by reaction  $\to {\mathcal C}^*$  is material property

Combustion stoechiometry = compromise high temperature vs low molar mass product



### Gas expansion Principles - impact of molecular weight

Assuming constant  $\mathcal{C}_{\mathcal{T}},~p^\circ$  and  $\mathcal{T}^\circ,$  the molar mass  $\mathcal M$  impacts

 $\bullet \ \text{specific impulse} \to \text{favor light gases}$ 

$$\mathcal{I}_{\text{sp}} = rac{\mathcal{C}_\mathcal{T}\mathcal{C}^*}{g} \sim rac{1}{\sqrt{\mathcal{M}}}$$

• thrust to power  $\rightarrow$  favor heavy gases

$$rac{\mathcal{T}}{\mathcal{P}}\sim rac{\dot{m}_e c_e}{\dot{m}_e c_e^2/2}\sim \sqrt{\mathcal{M}}$$

 ${\ensuremath{\bullet}}$  thrust to area/size  $\rightarrow$  more or less independent

$$rac{\mathcal{T}}{\mathcal{A}} \sim rac{\dot{m_e} v_e}{\dot{m_e} / 
ho_e v_e} \sim 
ho_e v_e^2 \sim rac{\mathcal{M}}{\sqrt{\mathcal{M}}^2}$$



#### Gas expansion Principles - impact of area ratio and feed pressure

#### Specific impulse variations

- $\mathcal{C}_{\mathcal{T}}$  increases with pressure ratio, *i.e.* with altitude and feed pressure  $p^{\circ}$
- $\bullet~ \mathcal{C}_\mathcal{T}$  maximal and independent of feed pressure in vacuum
- characteristic velocity independent of  $p^{\circ}$
- mass flow per unit area  $\sim p^{\circ}$

#### Launchers

- high feed pressure to maximise thrust coefficient and mass flow
- area ratio is chosen via compromise over altitudes

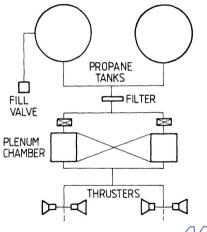
#### Space thrusters

- $\mathcal{I}_{sp}$  independent of feed pressure  $p^{\circ}$
- $\bullet~$  very high area ratios to maximise  $\mathcal{C}_\mathcal{T}$
- feed pressure determined by size / engine weight considerations



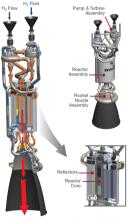
#### Gas expansion Thermal rockets - cold gas

- non-reacting gas:  $N_2$ , Ar, Fr,  $C_3H_8$
- temperature controlled high pressure reservoir
- low specific impulse  $\sim 50s$
- thrust levels  $\sim$  20 mN
- pulsed for modulation of average thrust
- precise control of position





### Gas expansion Thermal rockets - thermonuclear



NASA's Nuclear Thermal Propulsion Engine System, of which BWXT is providing support for reactor and fuel design and analysis.



- pressurized gas heated by nuclear reactor
- very high specific impulse  $\mathcal{I}_{sp} = 500 \ s \dots 900 \ s$ 
  - low mass gases such as  $H_2 \rightarrow \text{high } \mathcal{R}$
  - temperature not determined by combustion
- high thrust  $\mathcal{T} \approx 100 \ kN$
- online thrust control
- currently investigated concept for space exploration, orbit insertion, ...

### Gas expansion Thermal rockets - - NERVA XE

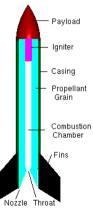
Nuclear Engine for Rocket Vehicle Application (NERVA)

- research engine at NASA
- vacuum thrust T = 246 kN
- Chamber pressure  $p^{\circ} = 3.861 MPa$
- vacuum  $\mathcal{I}_{sp} = 710 \dots 841 \ s$  (SLS vs vacuum)
- dry weight: 18 tonnes
- thermal power:  $\mathcal{P} = 1.1 \ MW$





### Gas expansion Solid propellant - operation

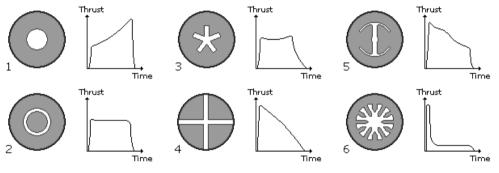


Solid Propellant Rocket

TAT

- grain: paste of premixed oxidiser and fuel
- pyrotechnic start to single step burn
- pressure variation depends on mass flow generated by combustion
- thrust variation a priori determined by grain shape
- thermo-acoustic instabilities

#### Gas expansion Solid propellant - grain shape

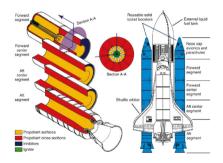






#### Gas expansion Solid propellant - space shuttle booster

- propellant mass  $m_p = 500$  tonne
- empty mass  $m_m = 91$  tonne
- T = 15 MN
- $I_{sp} = 242 \ s$
- reusable

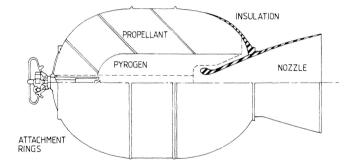




### Gas expansion Solid propellant - apogee kick motor

#### Intelsat V

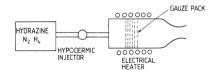
- $\Delta v = 2000 m/s$
- payload  $m_l \approx 1000 \ kg$
- propellant mass  $m_p \approx 900 \ kg$
- engine mass  $m_m \approx 1000 \ kg$
- $T = 70 \ kN$  during 40 s
- $\mathcal{I}_{sp} \approx 280s$





### Gas expansion Monopropellant liquid rocket - Principle

- operating principle
  - main propellant hydrazine  $N_2H_4$
  - pressurized reservoir
  - pulsed expansion over regulation valve
  - decomposition over heated catalyst bed
  - decomposition products  $N_2$ ,  $H_2$  and  $NH_3$
- can be combined with thermal heating (arcjet/resistojet)
- T > 10N modulated during operation by pulsing
- $\mathcal{I}_{sp} \approx 200 \ s$
- attitude control and station keeping (geostationary)





### Gas expansion Monopropellant liquid rocket - Astrium hydrazine

- T = 1 N
- $\mathcal{I}_{sp} = 210 \ s$
- $\dot{m}_e = 0.44g/s$
- Burn time = 50 hours
- $\bullet \ \ {\rm length} = 17 \ {\rm cm}$
- $A_e/A_t = 80$
- applications: small sattelites and deep space probes
  - attitude and orbit control
  - station keeping





### Gas expansion Monopropellant liquid rocket - Astrium hydrazine

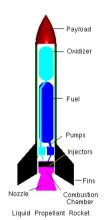
- T = 400N
- $\mathcal{I}_{sp} = 220s$
- Burn time : 30 minutes
- Length : 32 cm
- attitude control Ariane V





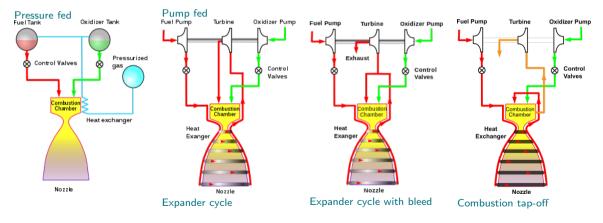
### Gas expansion Bipropellant liquid rocket

- combustion of pressurized fuel and oxidiser
- variants
  - pressure fed
  - pump fed
- $\mathcal{I}_{sp} = 300 \dots 400s$
- applications
  - launch (pump fed)
  - kick engines (pressure fed)
  - orbit and attitude control (pressure fed)
- $\bullet\,$  pogo: vibrations  $\leftrightarrow$  water hammer  $\leftrightarrow$  varying feed pressure  $\leftrightarrow$  varying thrust
- complex starting procedure



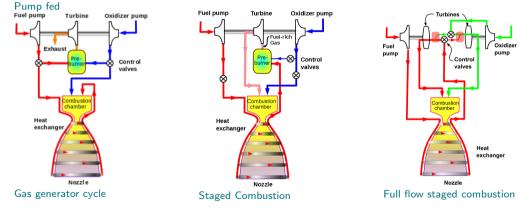


### Gas expansion Bipropellant liquid rocket - cycles





### Gas expansion Bipropellant liquid rocket - cycles





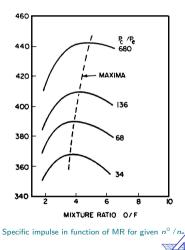
### Gas expansion Bipropellant liquid rocket - mixture ratio

#### Mixture ratio

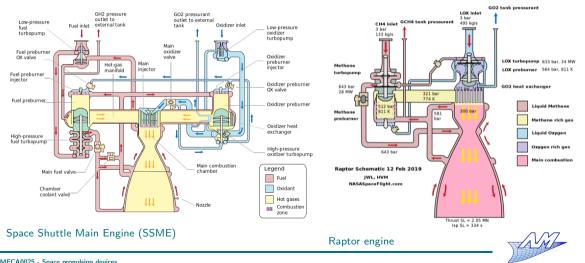
• oxidizer to fuel ratio

 $MR = rac{\dot{m}_o}{\dot{m}_f}$ 

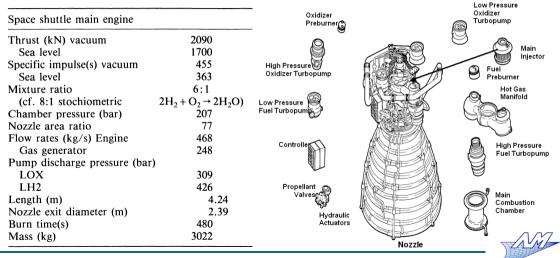
- optimal MR compromises
  - high combustion temperature
  - low average molecular weight of combustion product
- (almost?) never stoechiometric



#### Gas expansion Bipropellant liquid rocket - space shuttle main and raptor engine



#### Gas expansion Bipropellant liquid rocket - space shuttle main engine characteristics



### Gas expansion Bipropellant liquid rocket - Astrium S400

- pressure fed
- T = 400 N
- $\mathcal{I}_{sp} = 318 \ s$
- propellants: MMH /  $N_2O_4$
- apogee orbit injection (geostationary)
- orbit manoeuvers (deep space probes: Venus express, Artemis)



### Gas expansion Bipropellant liquid rocket - Astrium S10



- T = 10N
- $\mathcal{I}_{sp} = 291s$
- propellants: MMH /  $N_2O_4$
- nozzle expansion ratio : 150
- attitude/orbit control (large satellites: Arabsat)
- attitude/orbit control (deep space probes: Venus Express)







#### Introduction

Gas expansion

Electric propulsion Principles Gridded ion thrusters Hall effect thrusters

Air Breathing Electric Propulsion

#### Electric propulsion Principles - particles and electromagnetic forces

Electric field generated by particle charge density  $\rho_q$ 

$$\nabla \cdot \mathbf{E} = \frac{\rho_q}{\epsilon_0} = \frac{\sum_i n_i q_i}{\epsilon_0}$$

with  $n_i$  number density and  $q_i$  charge for particle i (electrons / ions) **Electric field and potential** 

 $\mathbf{E} = -\nabla V$ 

Lorentz force on particle with charge q in electric E and magnetic field B

 $mrac{doldsymbol{v}}{dt}=q\left(oldsymbol{\mathsf{E}}+oldsymbol{v} imesoldsymbol{\mathsf{B}}
ight)$ 

Linear acceleration subject to electric field E

$$m\frac{\partial \mathbf{v}}{\partial t} = q\mathbf{E} = -q\nabla V \qquad \Rightarrow \qquad m\mathbf{v} \cdot \frac{\partial \mathbf{v}}{\partial t} = -q\mathbf{v} \cdot \nabla V \qquad \Rightarrow \qquad m\Delta \frac{v^2}{2} = -q\Delta V$$

TAT

Particle energy expressed in eV

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### **Electric propulsion** Principles - particle and electromagnetic forces

Larmor precession: helicoidal motion subject to magnetic field

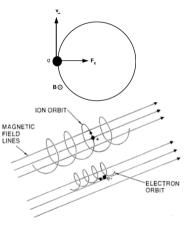
$$\begin{aligned} \frac{\partial \mathbf{v}_{p,\parallel}}{\partial t} &= 0 \qquad \qquad \Rightarrow \mathbf{v}_{p,\parallel}(t) = \mathbf{v}_{p,\parallel}(0) \\ \frac{\partial \mathbf{v}_{p,\perp}}{\partial t} &= \frac{q_p}{m_p} \mathbf{v}_{p,\perp} \times \mathbf{B} \qquad \qquad \Rightarrow \mathbf{v}_{p,\perp}(t) = e^{i\omega_\lambda t} \mathbf{v}_{p,\perp}(0) \end{aligned}$$

with (Larmor) frequency and radius

- frequency  $\omega_{\lambda} = \frac{|q_p|B}{m_p}$
- radius  $r_{\lambda} = \frac{|v_{\perp}|}{\omega_{\lambda}}$

 $\mbox{Drift velocity:}$  if  $\mbox{E} \bot \mbox{B} \to$  steady state velocity in equilibrium with Lorentz force

 $m{v}_{p,d} = rac{m{E} imes m{B}}{B^2}$ 





### Electric propulsion Principles - principles of thrusters

- ionise propellant gas
- accelerate heavy ions by electrostatic field
- thrust = reaction force
- thrust determined by ion flux/charge density, which is determined by
  - maximum potential difference of E-field
  - charge saturation (external E-field = E-field due to charge density)

Applications : requiring very high specific impulse

- orbital insertion
- deorbitalisation (demise)
- station keeping
- deep space missions



### Electric propulsion Principles - impact of atomic mass

Suppose same particle charge q, thruster potential  $\Delta V$ Effective ejection speed/specific impulse

$$v_e \leq \sqrt{rac{2q\Delta V}{m_p}} \sim rac{1}{\sqrt{m_p}}$$

#### Thrust to power

$$rac{\mathcal{T}}{\mathcal{P}} \sim rac{\dot{m} v_e}{\dot{m} v_e^2/2} \sim rac{1}{\mathcal{I}_{sp}} \sim \sqrt{m_p}$$

Power determines generator mass  $\rightarrow$  favor "lower"  $\mathcal{I}_{sp}$  and therefore "heavy" gases (Xenon, Krypton, Iodine) Thrust to area: suppose charge density saturated / fixed

$$rac{\mathcal{T}}{A} = rac{\dot{m}_e}{A} v_e \sim m_P v_e^2 \sim Cte$$



not impacted by particle mass

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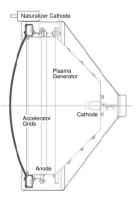
### Electric propulsion Gridded ion thrusters - operating principle

Principle: electrostatic acceleration of ions

- upstream generation of plasma stream
- screen grid removes electrons from plasma stream
- $\Delta V$  between screen and accelerator grids  $\rightarrow \mathbf{E} \rightarrow$  ion acceleration
- thrust limited by
  - maximum potential difference  $\Delta V$
  - ion charge density saturation (Child-Langmuir)
- naturaliser cathode: electron flux neutralises ion flux outside to ensure thruster charge neutrality

Characteristics

- $\mathcal{I}_{sp} \approx 2000 \dots 10000 \ s \ (v_e \approx 20 \dots 100 \ km/s \ !)$
- $\mathcal{T} \sim 10 \text{mN} \dots 1 \text{N}$





### Electric propulsion Gridded ion thrusters - Astrium RITA

- T = 150 mN
- $I_{sp} = 4000 \ s$
- $\mathcal{P} = 4kW$
- propellant : Xenon
- beam voltage :  $\Delta V = 1200 V$
- $\bullet~$  run time  $\geq$  20000 h
- thruster mass : 154 kg
- applications
  - Station keeping
  - orbit transfer
  - deep space missions





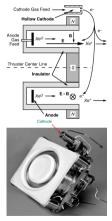
### Electric propulsion Hall effect thrusters - operating principle

#### Principle:

- external radial magnetic field  $B_r$  between annular poles
- electrons "feel"  $B_r$  while ions don't
- Larmor precession and drift confine electrons to bounce between poles and rotate fast in annular space
  - electron concentration  $\rightarrow$  axial electric field  $E_a$
  - collision w/ neutrals  $\rightarrow$  ionisation
- ions accelerated by axial electric field E<sub>a</sub>
- $\bullet\,$  no ion charge saturation due to presence of electrons  $\to$  higher flux density  $\to$  compact system
- axial migration of electrons to anode not fully understood
- electrons recombine outside with ions (thruster charge neutrality)

Characteristics

- $\mathcal{I}_{sp} \approx 1000 \dots 8000 \ s \ (v_e \approx 10 \ km/s \dots 80 \ km/s)$
- $\mathcal{T} \sim 40 \text{mN} \dots 5 \text{N}$



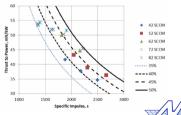


### Electric propulsion Hall effect thrusters - Busek BHT-1500



- Discharge Power: 1 kW ... 2 kW
- efficiency  $\sim 0.4...0.5 \rightarrow$  consumed power 2.5 kW...5 kW
- thruster Mass: 6.3 kg
- $\mathcal{T} = 70 \dots 180 \ mN$
- $I_{sp} = 1600...1860 \ s$







#### Outline Air Breathing Electric Propulsion

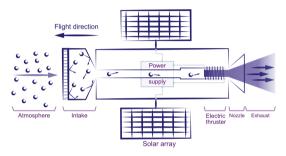
#### Introduction

Gas expansion

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### Air Breathing Electric Propulsion Hall effect thrusters - principles and challenges



Very low Earth Orbit: rarefied atmosphere

- ${\ensuremath{\, \bullet }}$  drag  $\rightarrow$  continuous thrust required to maintain speed
- main challenge: collecting individual molecules (no continuous regime)
- combination with electric propulsor
- ${\ensuremath{\, \bullet }}$  drag  $\rightarrow$  deorbiting at end of life assured

In between aeronautic and space propulsion